





A Fault Tolerance mechanism for Hybrid Scientific Workflows

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Workflow

A workflow is an abstraction that models a complex and modular working process as a set of steps and their inter-dependencies.



Hybrid workflows



A hybrid workflow is a workflow whose steps can span multiple, **heterogeneous**, and **independent** computing infrastructures.

Use case: Variant Calling Pipeline





A. Mulone, S. Awad, D. Chiarugi and M. Aldinucci,

"Porting the Variant Calling Pipeline for NGS data in cloud-HPC environment,"

2023 IEEE 47th Annual Computers, Software, and Applications Conference (COMPSAC), Torino, Italy, 2023, pp. 1858-1863, doi: <u>10.1109/COMPSAC57700.2023.00288</u>.

Use case: Variant Calling Pipeline

VM cloud (96 cores)





Hybrid execution (cloud+HPC)





Failures: soft error

Input data

Output data



Application raises an exception

Failures: fail-stop error

Input data

Output data



Facility shutdown

Failures: fail-stop error

Input data

Output data



Data lost Facility shutdown

Fault tolerance

A workflow manager is fault tolerant when it can continue the execution correctly even if a failure occurs.

Our contribution

if input data are available, then **retry** failed step otherwise **rollback** of steps which output data are lost

Recovery of the failure is delegated to a new sub-workflow. This sub-workflow is called recovery-workflow.

A synchronization mechanism is necessary to manage dependencies across concurrent recovery-workflows.

Workflow syntax

$$W ::= \langle l, D_1, t_d \rangle \parallel (W_1, W_2)$$

t ::=
$$\mu // t_1 \cdot t_2 // (t_1 | t_2) // (t_1 + t_2) // b t // 0$$

µ ::= exec(s,I, 0) // tran(v, l₂) // tran(v, l₁) // rec(x)

v ::= d //
$$m_s$$
 // $m_{d,1}$ // ok_{ms} // ok_d // err (x)

x ::= s // D, l // d, l // m_s, l

Workflow syntax

$$W ::= \langle 1, D_1, t_d \rangle \| (W_1, W_2)$$

Workflow syntax

$$W ::= \langle 1, D_1, t_d \rangle \parallel (W_1, W_2)$$

- \bullet t_w represents all traces in the workflow
- $M(s_i)$ is the mapping steps-locations
- d is the dataset
- $\bullet\ \rm m_{_{Si}}$ are the messages that driver sends to locations

Workflow syntax

$$W ::= \langle 1, D_1, t_d \rangle \parallel (W_1, W_2)$$

$$t ::= \mu \parallel t_1 \cdot t_2 \parallel (t_1 \mid t_2) \parallel (t_1 + t_2) \parallel ^{\flat} t \parallel 0$$

Workflow syntax

$$W ::= \langle l, D_{l}, t_{d} \rangle \parallel (W_{1}, W_{2})$$

 $t ::= \mu \parallel t_1 \cdot t_2 \parallel (t_1 \mid t_2) \parallel (t_1 + t_2) \parallel ^{\triangleright} t \parallel 0$

- Actions: **µ**
- Operators: ".", "|", "+"
- Empty trace 0
- Pointer denoting which is the current execution of the trace t: [▷] t

Workflow syntax

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$$\langle 1, D_1, t_d \rangle \parallel (W_1, W_2)$$

$$t ::= \mu \parallel t_1 \cdot t_2 \parallel (t_1 \mid t_2) \parallel (t_1 + t_2) \parallel ^{\triangleright} t \parallel 0$$

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$$v ::= d \parallel m_{s} \parallel m_{d,1} \parallel ok_{ms} \parallel ok_{d} \parallel err (x)$$

Workflow syntax

$$W ::= \langle 1, D_1, t_d \rangle \parallel (W_1, W_2)$$

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 $\mu ::= exec(s,I, 0) \parallel tran(v, l_2) \parallel tran(v, l_1) \parallel rec(x)$

 $v ::= d || m_{s} || m_{d,1} || ok_{ms} || ok_{d} || err (x)$

x ::= s || D, l || d, l || m_s, l

Formalization: rule actions

(INIT) $\frac{l = \mathcal{M}(s)}{\langle l_d, D_{l_d}, {}^{\triangleright} \operatorname{init}(t(s), l).t_d \rangle \mid \langle l, D_l, t \rangle \rightarrow \langle l_d, D_{l_d}, \operatorname{init}(t(s), l).{}^{\triangleright}t_d \rangle \mid \langle l, D_l, t \mid {}^{\triangleright}t(s) \rangle}$ $(\text{EXEC}) \quad \frac{\begin{cases} \text{if } I(s) \not\subset D_l \land m_s \in D_l, \ X = \{err(D,l)\} & \text{where } D = \{d \mid d \in I(s) \land d \notin D_l\} \\ \text{if } I(s) \subset D_l \ X = \{O(s), M_d\} & \text{where } M_d = \{m_{d,l} \mid d \in O(s)\} \lor X = \{err(s)\} \\ \hline \langle l, D_l, {}^{\triangleright} \texttt{exec}(s, I, O).t \rangle \rightarrow \langle l, (D_l \setminus \{m_s\}) \cup X, \texttt{exec}(s, I, O).{}^{\triangleright}t \rangle \end{cases}$ $(\text{TRANS}) \quad \frac{v \in D_{l_1}}{(1, D_{l_1})^{\triangleright} \operatorname{tran}(v, l_2).t_1} \land \quad \begin{cases} \text{if } v \in \{d, m_s\}, \text{ then } X = \emptyset \text{ and } V = \{v, ok_v\} \lor V = \{err(v, l_2)\} \\ \text{if } v = \{m_{d, l_1}, ok_d, ok_{m_s}\}, \text{ then } X = \{v\} \text{ and } V = \{v\} \end{cases}$ $\langle l_1, D_{l_1} \setminus X, \operatorname{tran}(v, l_2).^{\triangleright} t_1 \rangle \mid \langle l_2, \tilde{D}_{l_2} \cup V, \operatorname{tran}(v, l_1).^{\triangleright} t_2 \rangle$ $(\text{TRANSERR}) \quad \frac{v = err(x) \quad \wedge \quad err(x) \in D_l \quad \text{where } x = \{s, (D, l), (d, l), (m_s, l)\}}{\langle l, D_l, {}^{\triangleright} \texttt{tran}(v, l_d) . t \rangle \mid \langle l_d, D_{l_d}, {}^{\triangleright} \underline{\texttt{tran}(v, l)} . t_d \rangle \rightarrow }$ $\langle l, D_l \setminus \{v\}, \operatorname{tran}(v, l_d).^{\triangleright}t \rangle \mid \langle l_d, D_{l_d} \cup \{v\}, \underline{\operatorname{tran}}(v, l).^{\triangleright}t_d \mid {}^{\triangleright}\operatorname{rec}(x) \rangle$ (LOSTDATA) $\frac{err(d,l) \in D_{l_d} \land m_{d_i,l} \in D_{l_d}}{D_{l_i} = D_{l_i} \setminus \{m_{d_i,l}\}}$

Formalization: recovery rule actions

 $\left\langle l_d, D_{l_d} \setminus \{err(s)\}, t_d \mid \operatorname{rec}(s)^{\triangleright} \mid {}^{\triangleright}t_d(s \setminus t_{d_{I(s)}}) \right\rangle \mid \langle l, D_l, \mathbf{0} \mid t_s \rangle$ $\begin{array}{l} \forall d_i \in D \text{ such that } err(d_i,l), m_{d_i,l_j} \in D_{l_d} \\ \forall d_h \in D \text{ such that } err(d_h,l) \in D_{l_d} \text{ and } m_{d_h,l'}, d_h \notin D_{l_d} \\ \end{array} \quad d_h \in I(s_r) \end{array}$ (Rec(D)) $\left\langle l_{d}, D_{l_{d}}, t_{d} \mid {}^{\triangleright} \texttt{rec}(D, l) \right\rangle \mid \prod \left\langle l_{j}, D_{l_{j}}, t_{j} \right\rangle \mid \prod \left\langle l_{k}, D_{l_{k}}, t_{k} \right\rangle \mid \left\langle l, D_{l}, t \right\rangle \rightarrow$ $\left\langle l_{d}, D_{l_{d}} \setminus \{err(D, l)\}, t_{d} \mid \operatorname{rec}(D, l)^{\triangleright} \mid \stackrel{\sim}{\overset{\sim}{\vdash}} t_{d}(s) \mid \operatorname{rec}(s_{r}) \right\rangle \mid$ $\prod \left\langle l_j, D_{l_j}, t_j \mid {}^{\triangleright} \texttt{tran}(d_i, l) \right\rangle \mid \left\langle l, \emptyset, \mathbf{0} \mid t(s) \right\rangle$ $(\operatorname{REC}(D)) \quad \frac{\operatorname{err}(d,l), m_{d,l'} \in D_{l_d} \land l' \in \mathcal{M}(s_1) \quad d \in O(s_1)}{\langle l_d, D_{l_d}, t_d \mid {}^{\triangleright} \operatorname{rec}(d,l) \rangle \mid \langle l', D_{l'}, t' \rangle \mid \langle l, D_l, t \rangle \rightarrow} \langle l_d, D_{l_d} \setminus \{\operatorname{err}(d,l)\}, t_d \mid \operatorname{rec}(d,l)^{\triangleright} \rangle \mid \langle l', D_{l'}, t' \mid {}^{\triangleright} \operatorname{tran}(d,l) \rangle \mid}$ $\langle l, D_l, t | \operatorname{tran}(d, l').\operatorname{conf}(ok_d, l) \rangle$ $err(m_s, l) \in D_{l_d}$ $(\operatorname{Rec}(m_s))$ $\langle l_d, D_{l_d}, t_d \mid {}^{\triangleright} \operatorname{rec}(m_s, l) \rangle \mid \langle l, D_l, t \rangle \rightarrow$ $\langle l_d, D_{l_d} \setminus \{ err(m_s, l) \}, t_d \mid rec(d, l)^{\triangleright} tran(m_s, l) . \underline{conf}(ok_{m_s}, l) \rangle \mid$ $\langle l, D_l, t \mid \operatorname{tran}(m_s, l_d).\operatorname{conf}(ok_{m_s}, l) \rangle$

Example

Workflow



Example



Example



Experiment





- Fault tolerance mechanism implemented in StreamFlow (a hybrid WMS)
- Kubernetes with 4 workers
- Injected fail-stop errors on Merge step

Conclusions

Mixed different fault tolerance mechanisms

 π Introduced a semantics for fault tolerant hybrid workflows

Implemented the mechanism in StreamFlow, a hybrid workflow system

Future works



Deep performance study about the implemented
mechanism in StreamFlow

- Extend the semantics with workflow loop
- Support non-deterministic workflows